The Secrets of Salient Object Segmentation

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Paper Recap

Fixation Prediction

- 1. In fixation experiments, saliency is expressed as eye gaze points.
- 2. The goal of algorithms is to compute a "saliency map" that simulates the eye movement behaviors of human while looking at the image. (to capture eye gaze pattern)
- 3. Not pixel-accurate: Eye tracking devices are normally imprecise. Recorded fixation locations can go up to 1, or over 30 pixels.
- 4. ROC Area Under the Curve (AUC) is used to evaluate the quality of prediction against the human ground-truth.





Salient Object Segmentation

- 1. In Salient Object Segmentation experiments, saliency is what **image annotators believe** as **visually significant areas** in images.
- 2. The goal of algorithm is to generate a map that matches the annotated salient object mask. (annotators' perception)
- 3. Ground truth is pixel-accurate and region-based.
- 4. Distinct set of algorithms are developed.
- 5. Benchmark dataset: FT, IS.





A Novel Dataset: Pascal-S

- 1. Existing datasets are weak: Dataset design bias.
 - A. The FT dataset has unnaturally strong color contrast.
 - B. Intentionally filter images with blur object boundaries.
 - C. Image Annotation and Image Selection are not independent.
 - D. Unfortunately, most salient object segmentation algorithms report their result on the FT dataset with a large margin over fixation algorithms.
 - E. Most importantly, after removal of center bias and the dataset design bias, the performance gap between salient object segmentation algorithms and fixation algorithms is mostly reduced.
- 2. Propose a novel dataset: Pascal-S
 - A. Augmented 850 existing images from PASCAL 2010 dataset
 - B. Ground truth labeling of Eye fixations and salient object segmentation
 - C. Free of *dataset design bias*: the image selection and image annotation are kept *independent*



A Novel Model: CPMC + Fixation

- 1. Phrase One: object candidate proposal
 - A. Achieved by the **unsupervised framework** called CPMC (segmentation algorithm).
 - B. No need of category specific knowledge.
 - C. Output a pool of object candidates with their "objectness" score disregarded.
- 2. Phrase Two: segments selection process based on estimated saliency map
 - A. Achieved by learning a scoring function for each object candidate (fixation algorithm).
 - B. Input shape feature of object candidates and spatial distribution of fixations within (fixation map).
 - C. Output the **overlapping score** of the proposed region with respect to the ground-truth.
- **3**. This simple combination results in a novel salient object segmentation method that outperforms *all* previous methods by a large margin.

Experiments



Fig. F-measure of all algorithms on Pascal-S dataset. K = 20.

Experiments (cont.)

K=20	PASCAL-S	IS	FT
Fixation Model Used	GBVS	GBVS	GBVS
F-Measure	0.7457	0.7264	0.9097
Improvements	+11.82	+7.06	+2.47
Best SalObj Model	PCAS	PCAS	SF
F-Measure	0.6275	0.6558	0.8850

Fig. Comparison of Best Performing Results on Other Segmentation Datasets



Fig. Performance of CPMC+Fixation Model under Various Quantities of Object Candidates K

Supplementary Experiments

Experiment #1

- 1. Idea: measure overall performance of the method in IS dataset (250 images)
- 2. The only third-party dataset where both fixation map and salient object segmentation labeling are available
- 3. Directly trained on IS and test on IS. Outcome is unexpected

Algorithm	sf	gc	pcas	ft	HumanFix
Performance	0.5022	0.5749	0.6050	0.4296	0.5837
Algorithm	CPMC+aws	CPMC+aim	CPMC+sig	CPMC+dva	CPMC+gbvs

4. CPMC+gbvs is worse than pcas, the straight forward salient object segmentation algorithm.

Experiment #2

- 1. Idea: measure the cross-dataset performance of the method
- 2. Trained on PASCAL-S dataset and then test it on IS dataset

Algorithm	sf	gc	pcas	ft	CPMC+gbvs
Performance	0.4938	0.5698	0.6116	0.4183	0.4831

3. Trained on IS dataset and then test it on PASCAL-S dataset

Conclusion & Discussion

Conclusion

- 1. Discovers a new type of dataset bias: dataset design bias.
- 2. Augments a new dataset with both fixation prediction and salient object segmentation labelling.
- 3. Proposes a new state-of-the-art method that
 - A. Simply combines the existing segmentation algorithm (CPMC) and fixation algorithms
 - B. Outperforms all other models on all segmentation datasets.
- 4. Supplementary experiments show that this method is not robust when its parameters are not well-tuned.

Discussion







Fig. Performance of <u>CPMC+Fixation</u> Model under Various Quantities of Object Candidates K

Fig. F-measure of all algorithms on Pascal-S dataset. K = 20.