# HICO: A Benchmark for Recognizing Human-Object Interactions in Images

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### HICO

~47,000 labeled images in 600 human-object interaction (HOI) categories



#### Object-Verb

- sports ball block X
- sports ball carry V
- sports ball hold V
- sports ball sign X
- wine glass fill ?
- apple peel ?

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#### **Human-Object Interaction Prediction**





#### Horse-Ride Horse-Sit on

# Evaluate the best proposed model

### Pipeline of the DNN Model

binary SVM per category



### Weird Output Distribution

Imagenet





x-axis: number of prediction labels y-axis: % of testing sets







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Imagenet





x-axis: number of prediction labels y-axis: % of testing sets

Object





A lot of testing images are not predicted as any category.

# Long Tail Distribution of Categories



#### Weighted Loss for Unbalanced Dataset

**Binary Classifier for Class 1** 

Positive Sample Negative Sample

Class 1 Class 2, 3, ...,600

Total Loss =  $w_p$  \* loss on positive samples +  $w_n$  \* loss on negative samples

### Experiments on w\_p/w\_n

w_p/w_n	mAP (%)
1	18.58
3	19.05
10	19.39
30	19.24

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	mAP
Random	0.57
RF [36]	7.30
FV [29]	4.21
DNN (ImageNet)	18.58
DNN (fine-tune V)	17.65
DNN (fine-tune O)	19.38
DNN (fine-tune VO)	18.08
HOCNN	4.90

Our Implementation: End-to-End Network

#### **Multi-Label Classification**



### **Experimental Setting**

#### CNN Model:

- Inception v3
- softmax layer -> logistic sigmoid layer
- number of classes -> 600

#### Training:

- Use pretrained model on ImageNet
- Fine-tune only the last layer
- Optimizer: Adam
- Learning rate: 0.001
- Batch size: 64
- Epochs: 10

#### Source Code

- Implemented in TensorFlow
- TF-Slim Library
- Github: <u>https://github.com/chiawen/multi-label-classification-hico</u>

chiawen / multi-label-classifi	cation-hico	•	Ounwatch -	1 🛨 Sta	r 0	Ϋ́ Fork
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#### ം Usage

First, extract the filenames and labels of the training set and the testing set.

\$ python process\_hico\_labels.py

Second, convert the image files and annotations to TFRecords.

\$ python hico\_to\_tfrecords.py

To fine-tune the last layer of Inception v3 for 10 epochs:

\$ python finetune.py

To evaluate mAP scores on the testing set:

\$ python eval.py

#### Performance

Method	mAP (%)
DNN (fine-tune O)	19.38
DNN (ImageNet) + weighted loss (ours)	19.39
Inception V3 + fine-tune (ours)	26.31

# **Related Work**

#### Performance of HICO Benchmark

Arun Mallya and Svetlana Lazebnik. Learning Models for Actions and Person-Object Interactions with Transfer to Question Answering. In *ECCV*, 2016.

1	Method	Full Im.	Bbox	MIL	Wtd. Loss	mAP
a)	AlexNet+SVM [16]	$\checkmark$				19.4
	VGG-16, full image	✓				29.4
b)	VGG-16, bounding box		$\checkmark$	$\checkmark$		14.6
D)	$VGG-16, R^*CNN$		$\checkmark$	$\checkmark$		28.5
	VGG-16, Scene-RCNN	$\checkmark$	$\checkmark$	$\checkmark$		29.0
	Fusion-1	~	$\checkmark$	$\checkmark$		33.6
c)	Fusion-1, weighted loss	~	$\checkmark$	$\checkmark$	$\checkmark$	36.0
	Fusion-2	✓	$\checkmark$	$\checkmark$		33.8
	Fusion-2, weighted loss	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	36.1

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