

People Watching: Human Actions as a Cue for Single-View Geometry

David Fouhey, Vincent Delaitre,
Abhinav Gupta, Alexei Efros, Ivan Laptev, Josef Sivic

Presented by Ashwini Venkatesh

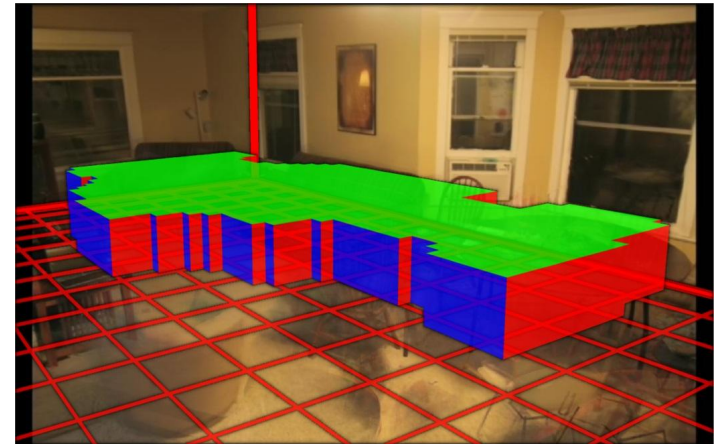


Where are the people?

People – Cues not Clutter



Goal – Inverse Problem



Clutter

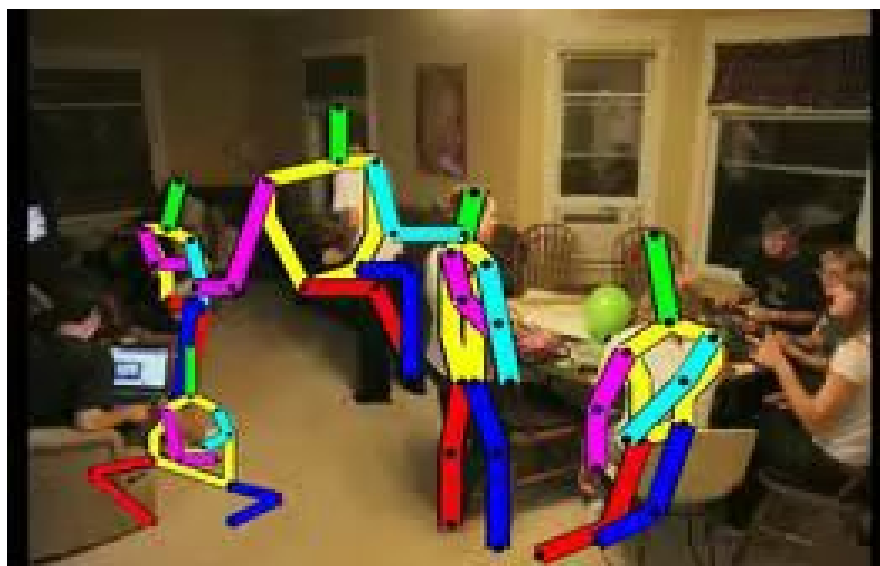


Sensors !

Approach



Timelapse



Pose Detections

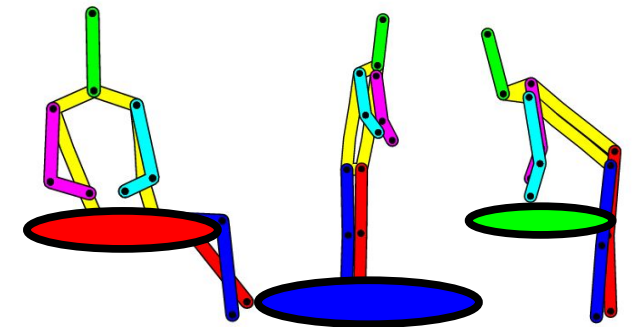
Approach



Timelapse



Pose Detections



Estimate Functional Regions from Poses

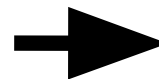
Approach



Timelapse



Pose Detections



Functional Regions

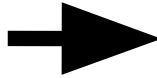


3D Room Hypotheses From Appearance

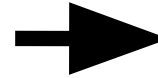
Approach



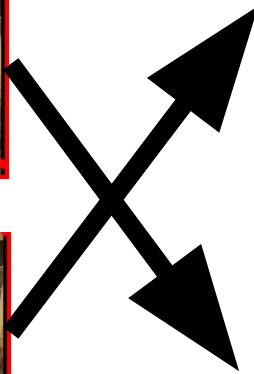
Timelapse



Pose Detections



Functional Regions



#1



#49

Score 3D Room Hypotheses With Appearances + Affordances

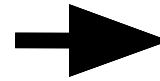
Approach



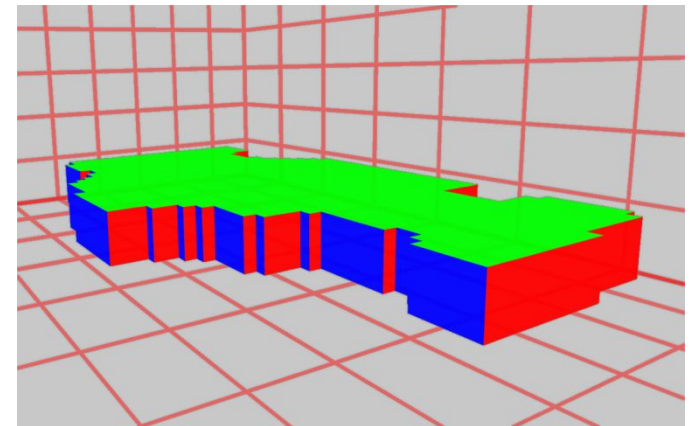
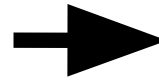
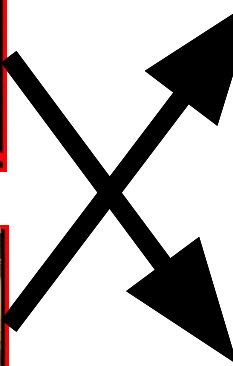
Timelapse



Pose Detections



Functional Regions



Estimate
Free-Space

Approach



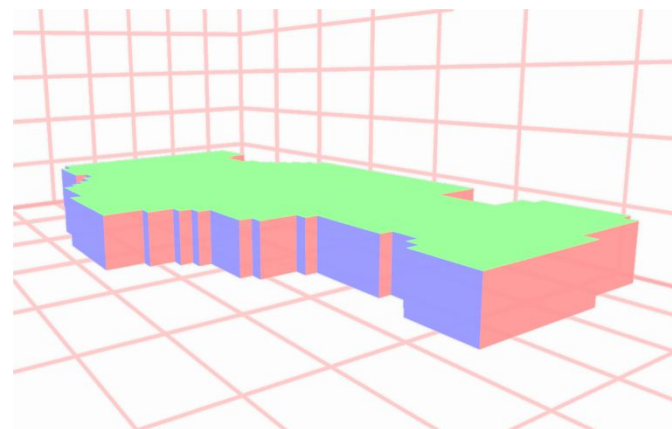
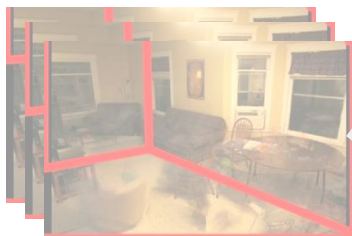
Timelapse



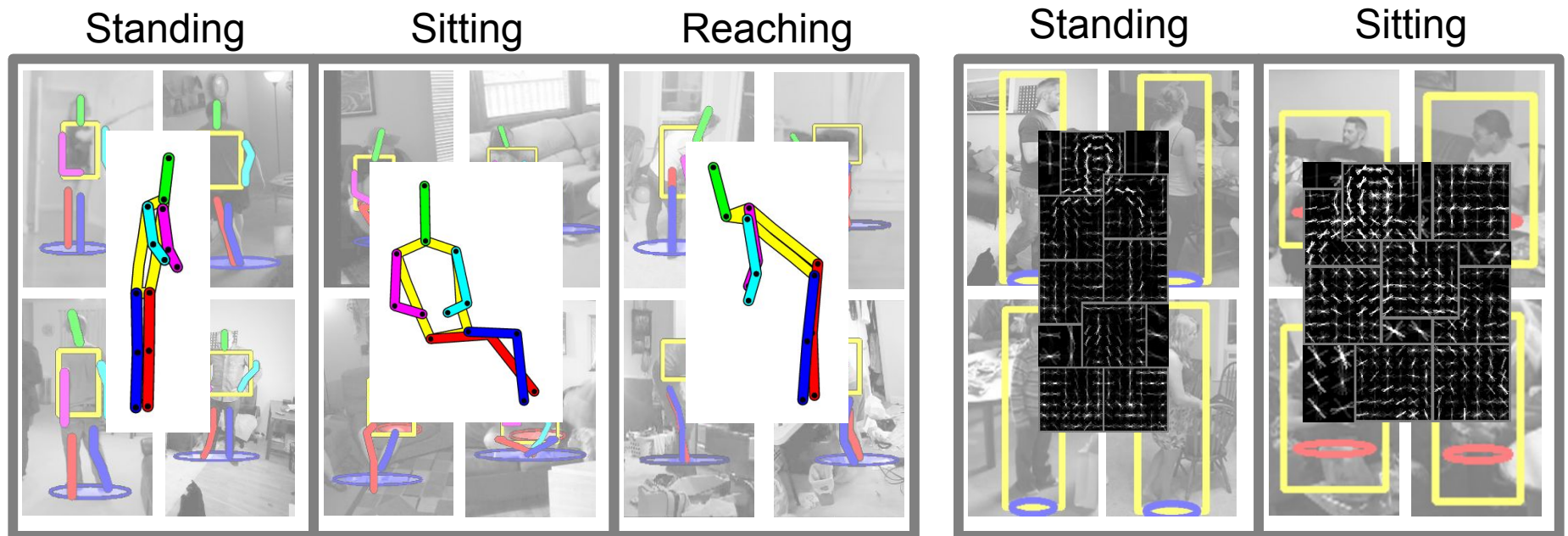
Pose Detections



Functional Regions



Detecting Human Actions



Articulated Pose Estimator

Deformable Parts Model

Train Separate Detectors for Each Pose

Approach



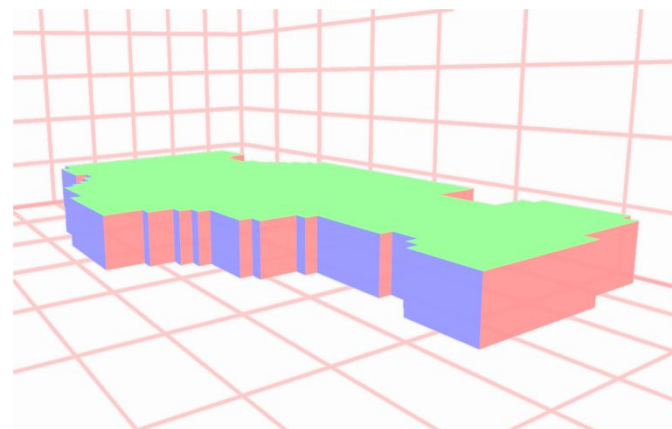
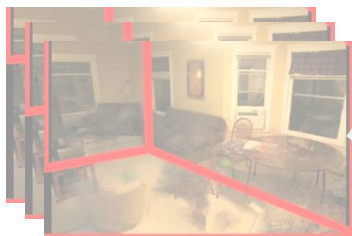
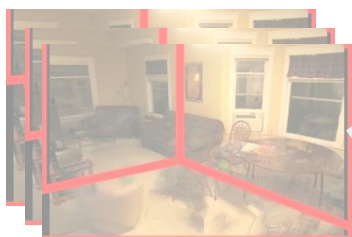
Timelapse



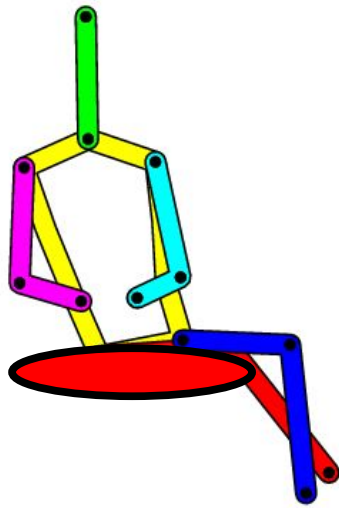
Pose Detections



Functional Regions

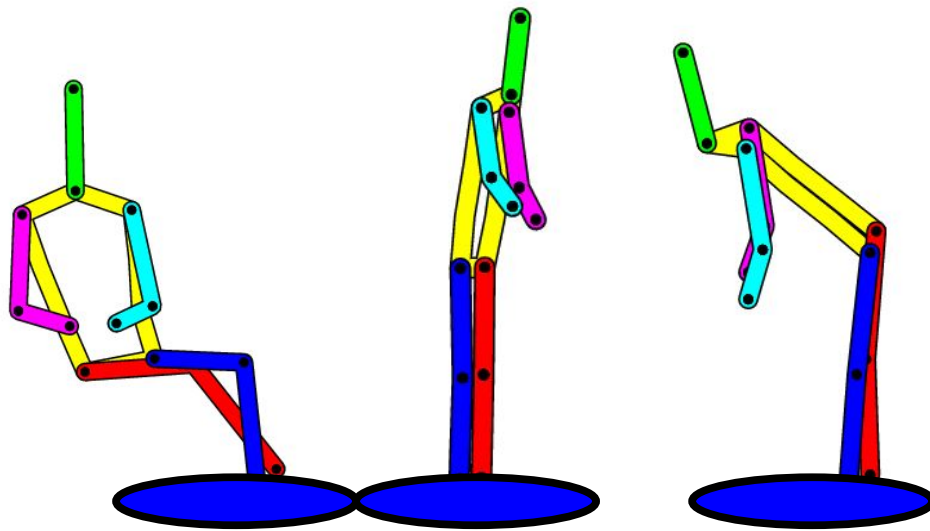


From Poses to Functional Regions



Sittable Regions at Pelvic Joint

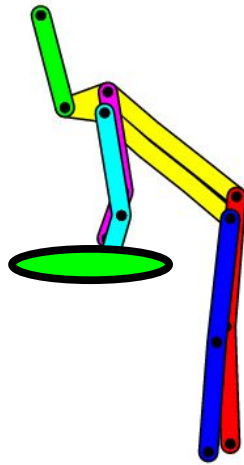
From Poses to Functional Regions



Walkable Regions at Feet



From Poses to Functional Regions



Reachable Regions at Hands



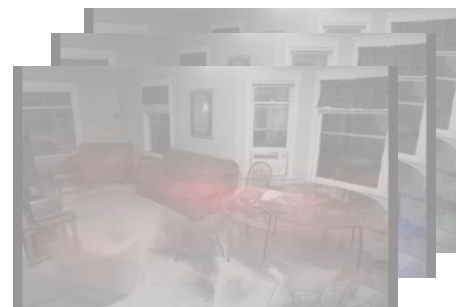
Approach



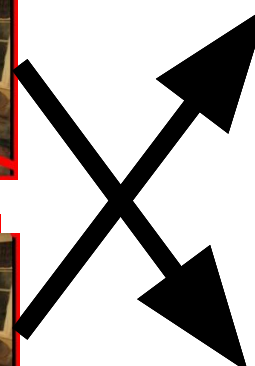
Timelapse



Pose Detections



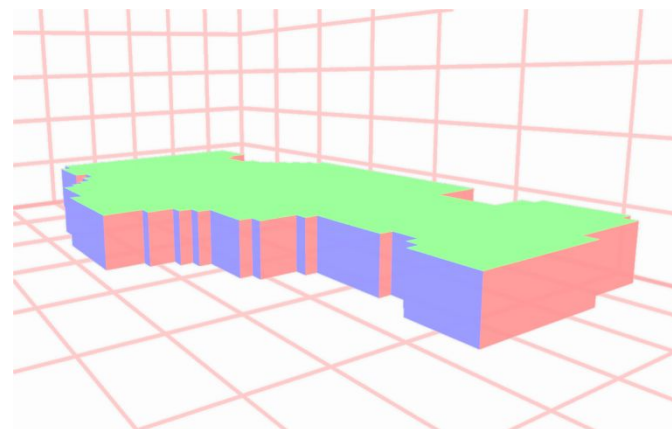
Functional Regions



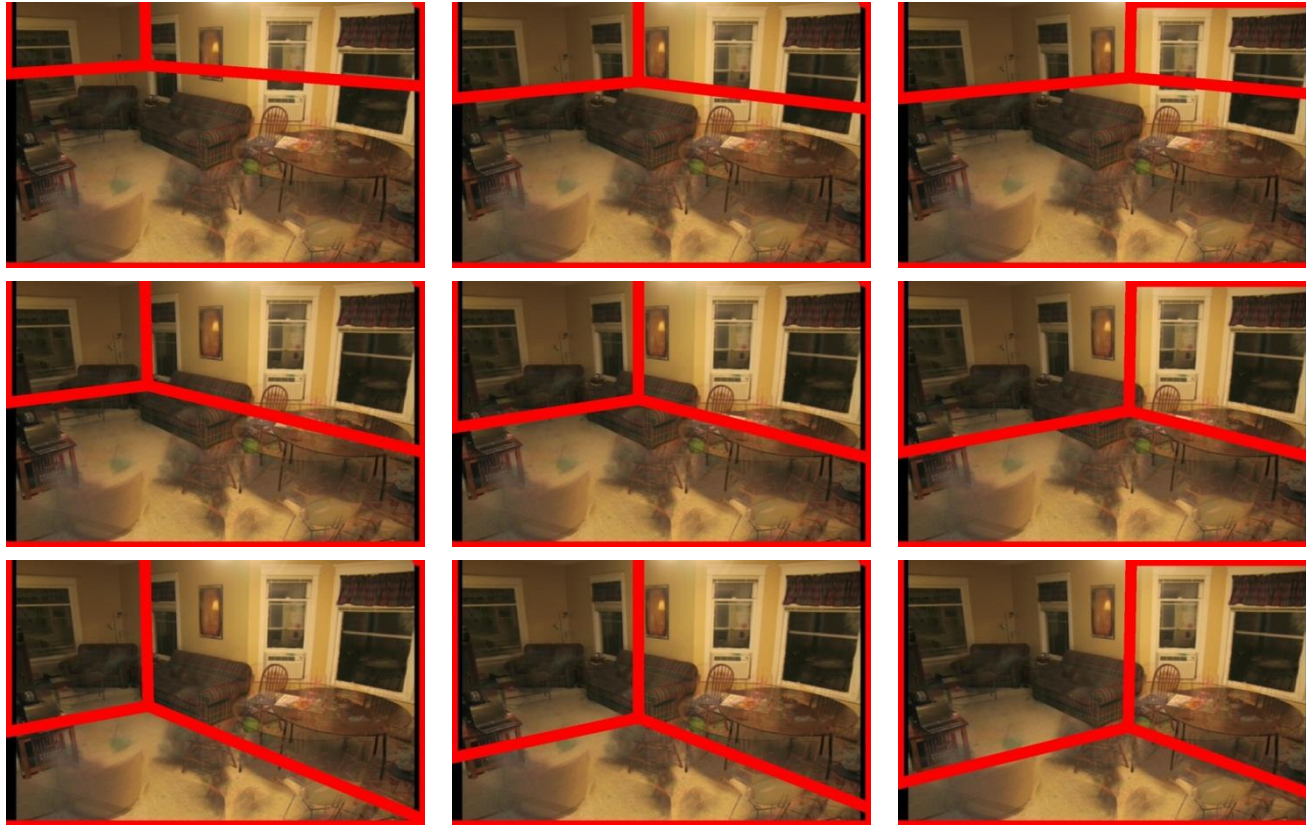
#1



#49



3D Room Hypotheses



Vanishing-point aligned hypotheses

Constraints

Containment

Volume occupied by human should be inside a room

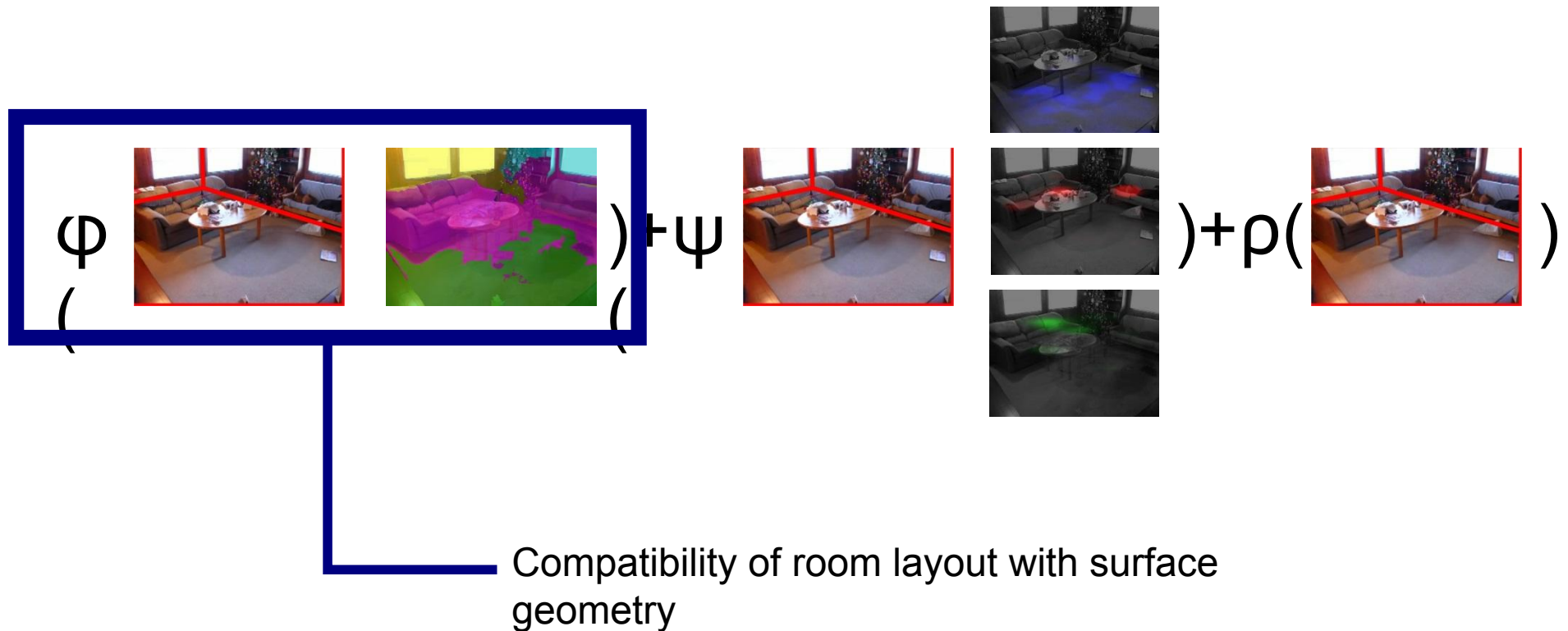
Free Space

Volume occupied by human cannot intersect any object in the room

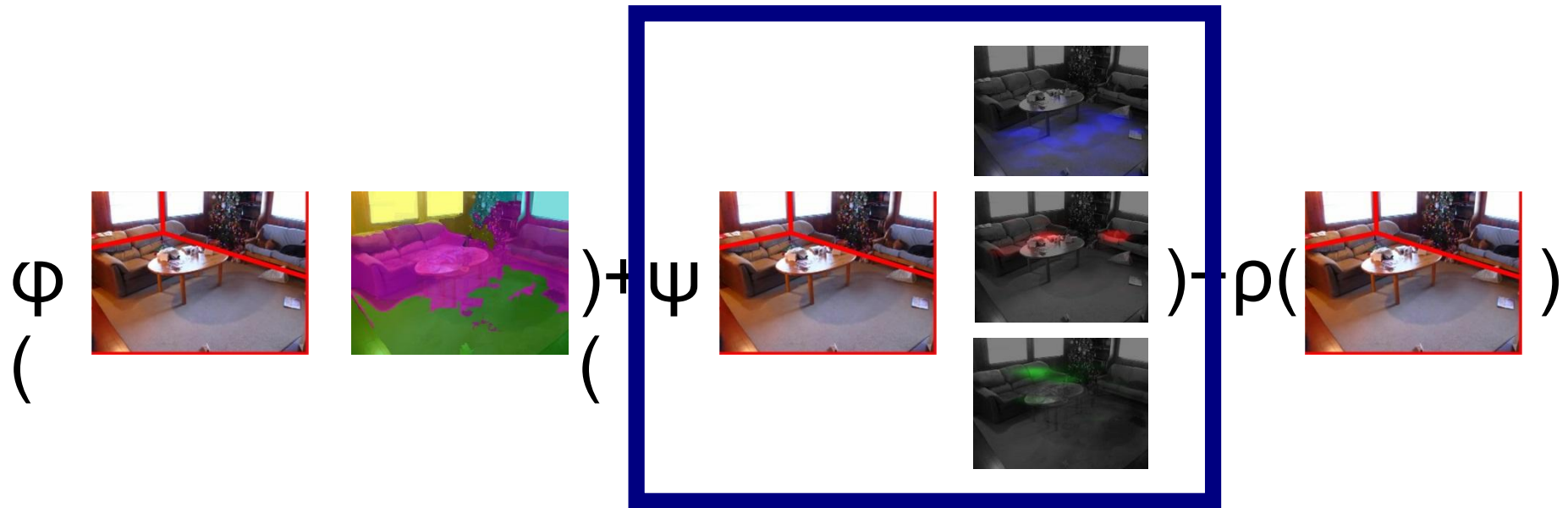
Support

Object surfaces which can make the pose physically stable

Putting it together – picking a room

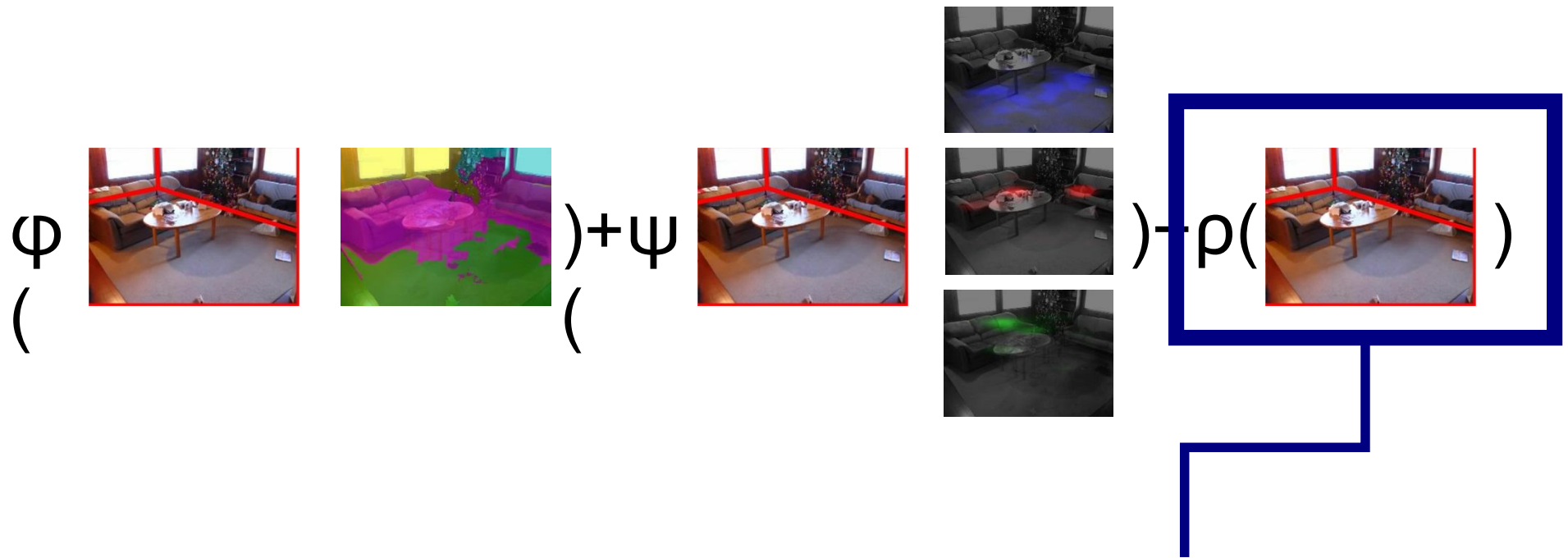


Putting it together – picking a room



Compatibility of human poses
and room layout

Putting it together – picking a room



Relative room size regularizer

Reranking Results

Appearance
Alone

#1



Score = -1.7754

...

#82



Score = -1.8859

Appearance +
People

#1



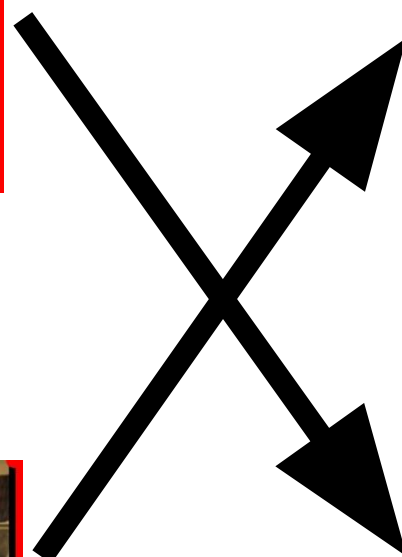
Score = -1.8865

...

#49



Score = -2.0319



Approach



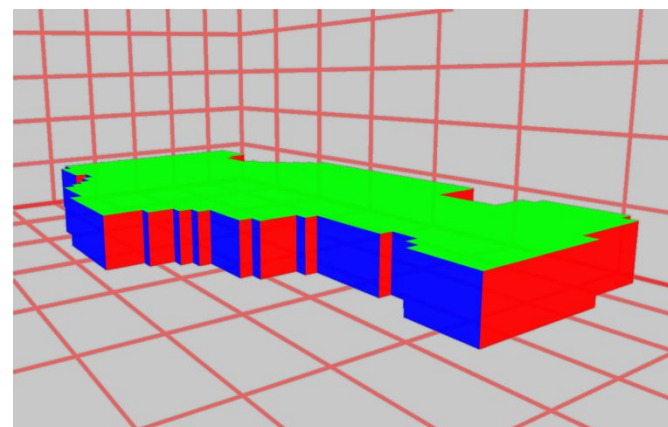
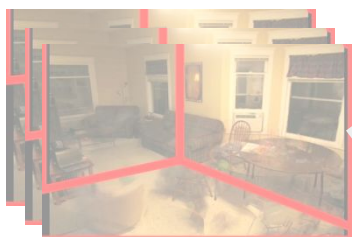
Timelapse



Pose Detections

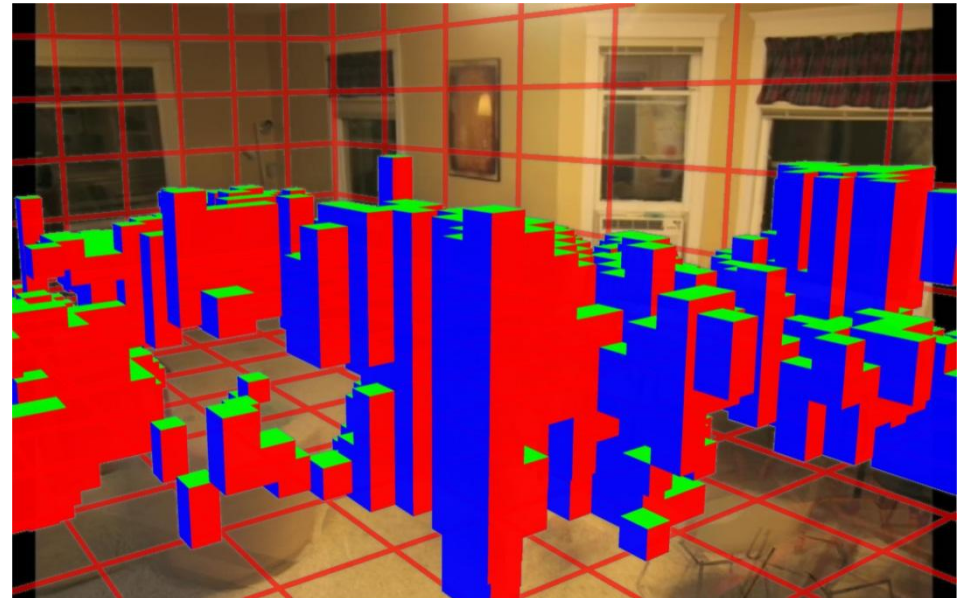
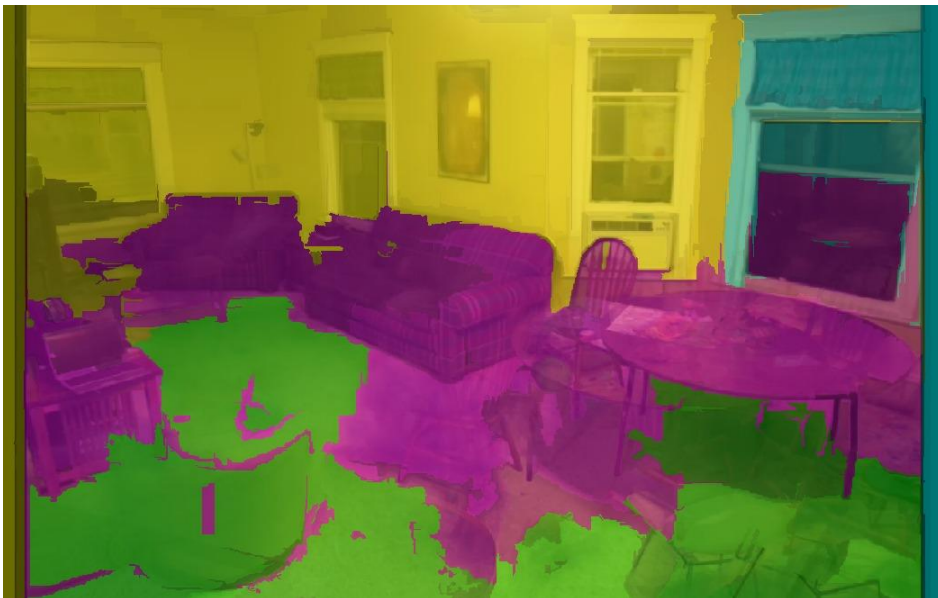


Functional Regions



Estimate
Free-Space

Estimating free space



LEGEND

Floor

Wall 1

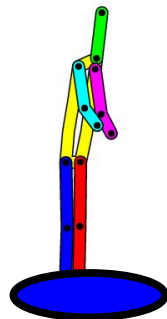
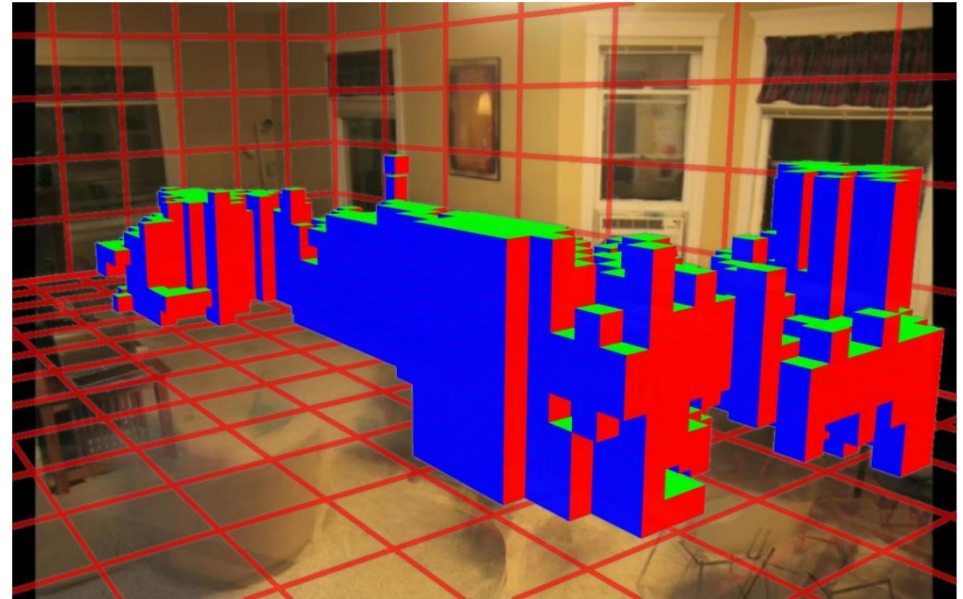
Wall 2

Wall 3

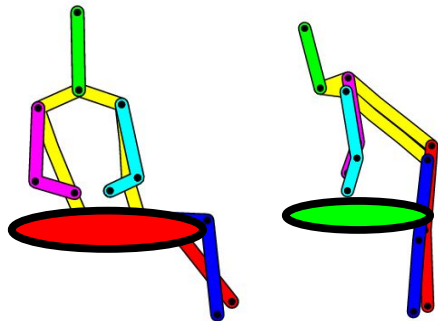
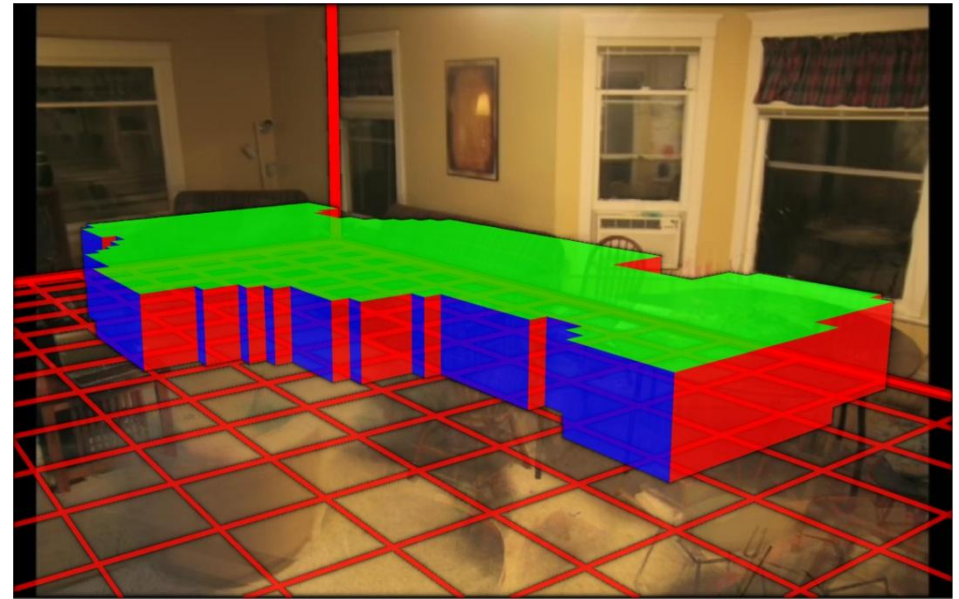
Ceiling

Clutter

Estimating Free Space

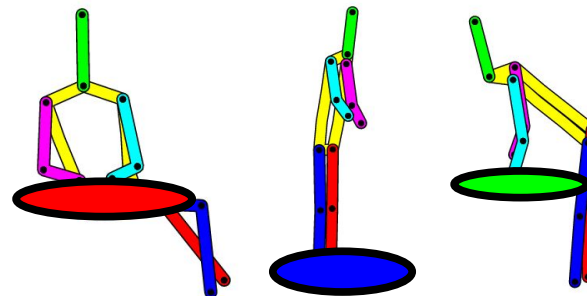


Estimating Free Space



Results

Qualitative Example

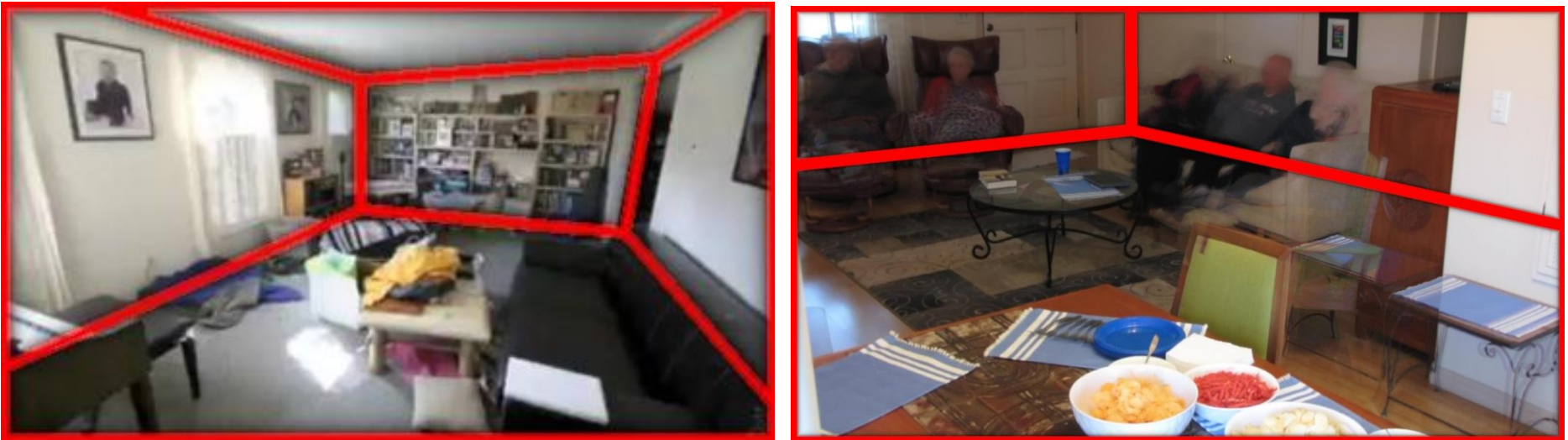


Qualitative Results



Appearance Alone

Qualitative Results



Appearance + People

Single Images with People



Appearance Alone

Single Images with People



Appearance + People

Quantitative Results

	Location	Appearance Only		People Only	Appearance + People
		Lee et al. '09	Hedau et al. '09		
Timelapses	64.1%	70.4%	74.9%	70.8%	82.5%
Single Image	66.4%	71.3%	77.0%		79.6%

Discussion Points

1. Do some human action exceptions such as can sitting on table, standing on a sofa cause trouble for the algorithm?
2. Role of background subtraction during testing
3. Semantic relationships between humans and objects
4. Performance on odd-shaped rooms and outdoor scenes
5. Evaluation metric used - only evaluates the 3D room scene and the free space estimate